

On the Use of Machine-Learning for Runtime Monitoring



Mitra Nasri

Agenda

- My perspectives on
 - ML for RT: **Learning-enabled** safety-critical real-time systems
 - ML for RT: **Learning-assisted** safety-critical real-time systems
- ML-based runtime monitoring of real-time systems

Learning-enabled safety-critical real-time systems

(RT for ML)

How to build safe real-time systems that use machine-learning or AI components?

the behavior of the
deployed system

- End-to-end response time
- Actuation instants
- Messages on the CAN bus
- ...

meets

its specifications

- Respecting deadlines
- Performing periodic actuations
- Respecting safety properties
- ...



Realization of
the system

Learning-enabled safety-critical real-time systems

(RT for ML)

How to build efficient (time-predictable) real-time systems that use machine-learning or AI components?

Challenges in modeling timing behavior of ML/AI applications

Challenges

- ML/AI applications often require a hierarchy of middleware and intermediate runtime engines which result in a complex partially-observable timing behavior
 - **Low observability**: Parts of the runtime environment are often not fully observable
 - **High variability and large configuration space** → reduced extendibility of studies or tool sets
 - **Dynamic migration of SW over HW resources**: These middleware often use greedy approaches to dispatch jobs based on availability of resources
 - **No or poor support for execution isolation**: OS-assisted isolation might be possible but that often requires changes in the middleware
 - **Dealing with SW or ML-Model upgrades**: How updates and upgrades impact the fidelity (or parameters of) the timing models?

Learning-enabled safety-critical real-time systems

(RT for ML)

How to build efficient (time-predictable) real-time systems that use machine-learning or AI components?

Challenges in modeling timing behavior of ML/AI applications

Verifying properties

Challenges

- **Lack of scalability:**
 - The response-time analysis problem is NP-Hard even in very simple cases
 - Common verification engines (UPPAAL, ...) struggle to verify timing properties like response times in a scalable way
 - Modeling an RTA problem in a verification engine requires expertise (it is prone to errors)
 - These errors are harder to spot because the proof of correctness of the model are often skipped in this type of publications
- **Lack of tools to analyze dynamic or flexible scheduling policies:** Our community has mostly focused on “good” policies (FP, EDF, ...), leaving out the wild world of middleware platforms designed by none RT-experts

Learning-enabled safety-critical real-time systems

(RT for ML)

How to build efficient (time-predictable) real-time systems that use machine-learning or AI components?

Challenges in modeling timing behavior of ML/AI applications

Verifying properties

SAG: Schedule Abstraction Graph Framework

<https://github.com/SAG-org>



Scalable RTA platform for a wide set of scheduling problems for Gang tasks, parallel DAGs, self-suspending tasks, and global scheduling of preemptive and non-preemptive tasks (+15 publications)

ReTA: A flexible DSL and analysis framework for user-defined scheduling problems

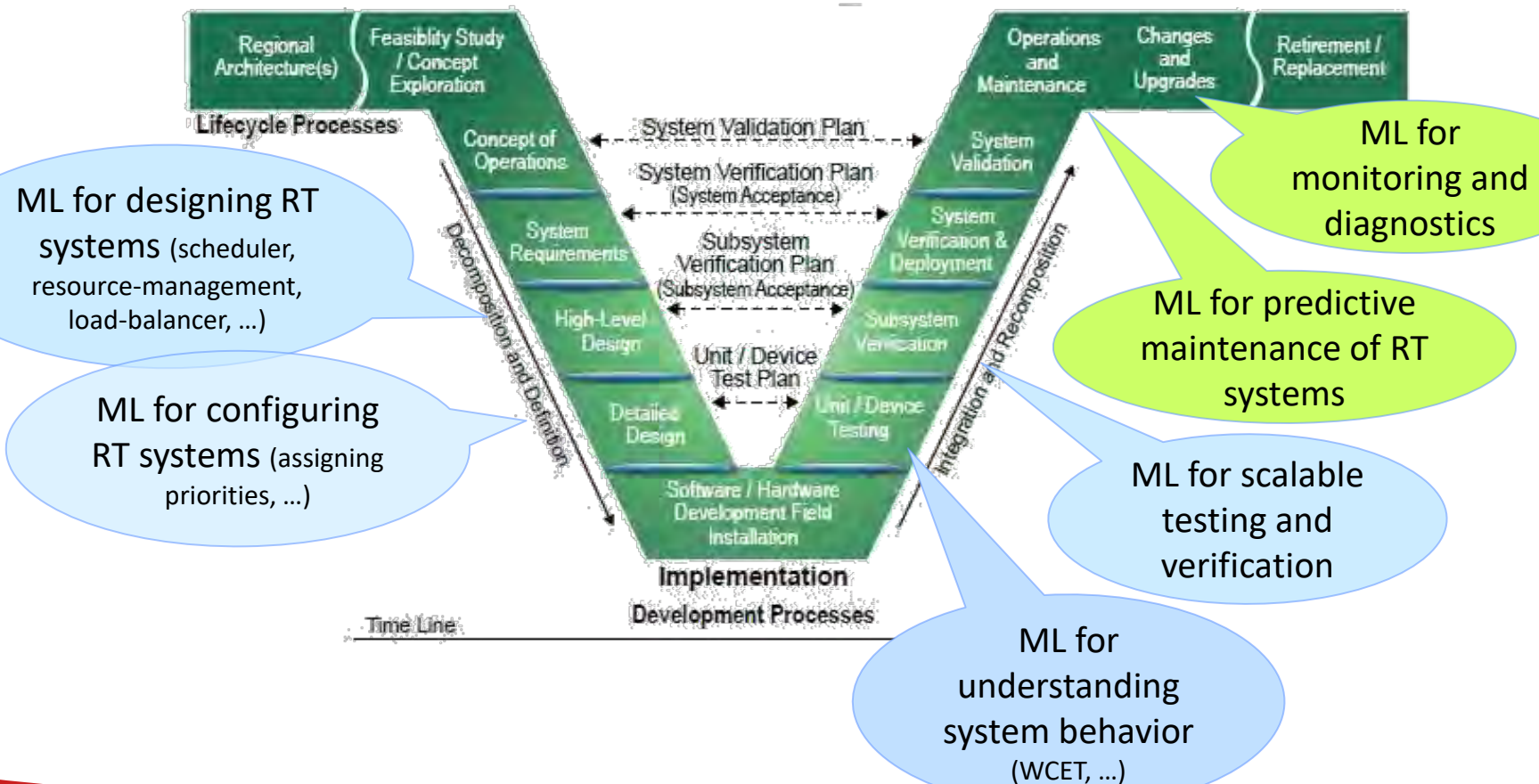
<https://github.com/porya-gohary/ReTA>



Learning-assisted safety-critical real-time systems

(ML for RT)

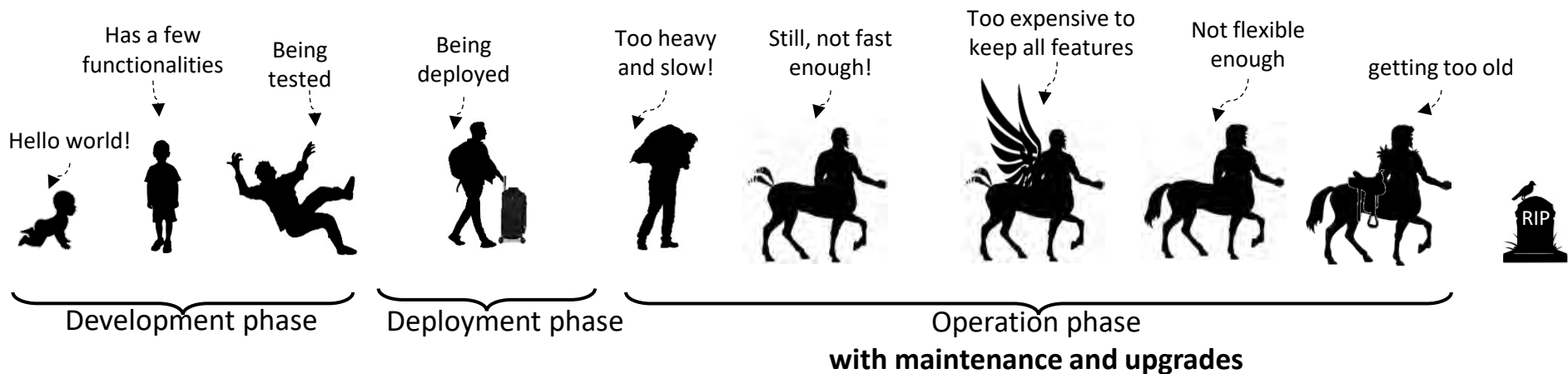
How can ML and AI technologies help us design better real-time systems?



Agenda

- My perspectives on
 - ML for RT: Learning-assisted safety-critical real-time systems
 - ML for RT: Learning-enabled safety-critical real-time systems
- **ML-based runtime monitoring of real-time systems**

Runtime monitoring, diagnosis, and runtime intervention



Finding “time bugs”

Deviations from the
**expected timing
behavior**

Runtime monitoring

Detecting **timing anomalies** and
security attacks that leave a trace on
the observable timing profile

Diagnosing the system after
applying a patch or an upgrade

A case study: runtime monitoring of “periodicity” property

A fundamental requirement in most real-time systems

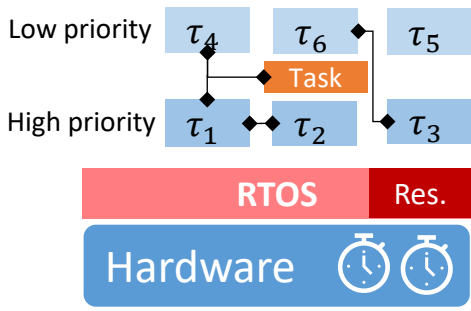
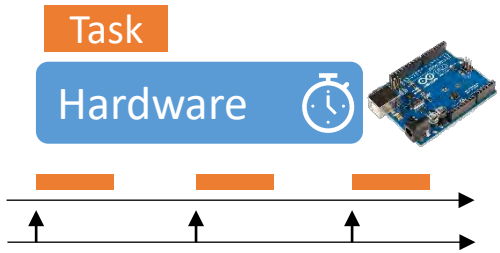
*“Do the activities that are supposed to be **periodic** happen periodically?”*

From our work at RTSS’2020:

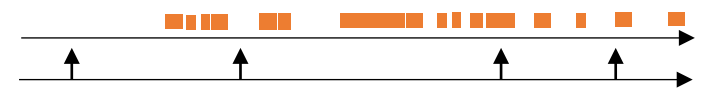
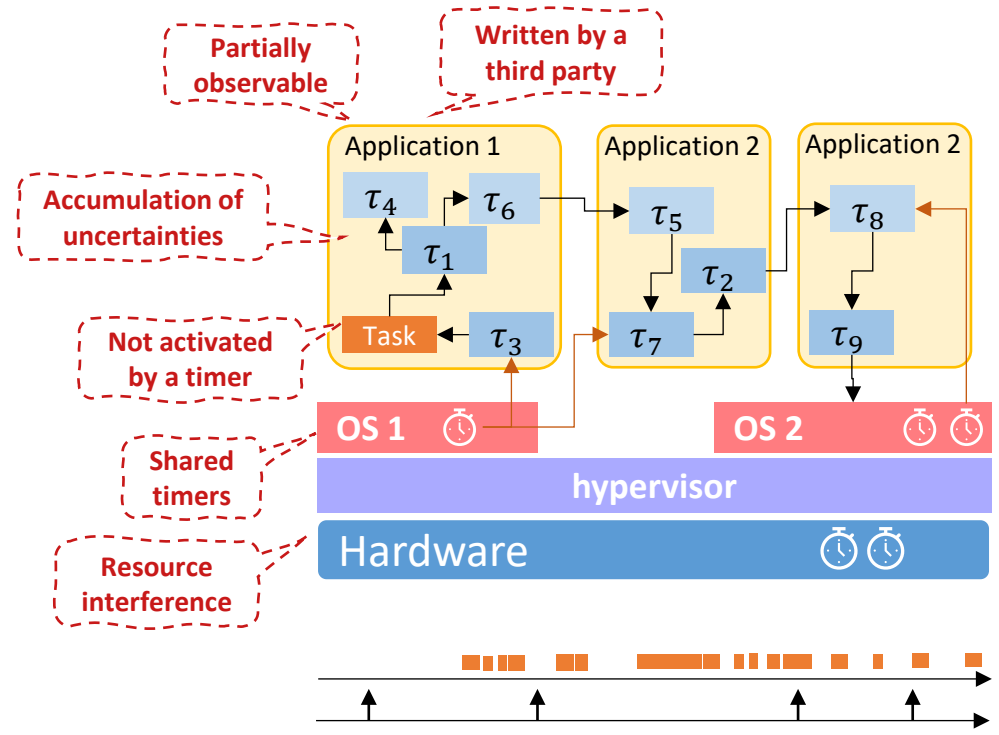
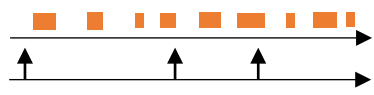
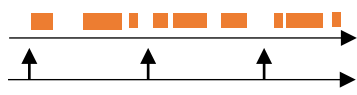
Serban Vadineanu and **Mitra Nasri**, “Robust and accurate period inference using regression-based techniques,” the IEEE Real-Time Systems Symposium (**RTSS’20**), 2020, pp. 358-370

Outstanding Paper Award [[paper](#) | [slides](#) | [repository](#)]

Why inferring period?



- Data dependency
- Release jitter
- Execution time variation
- Shared resources
- Overheads and delays
- ...



The period inference problem

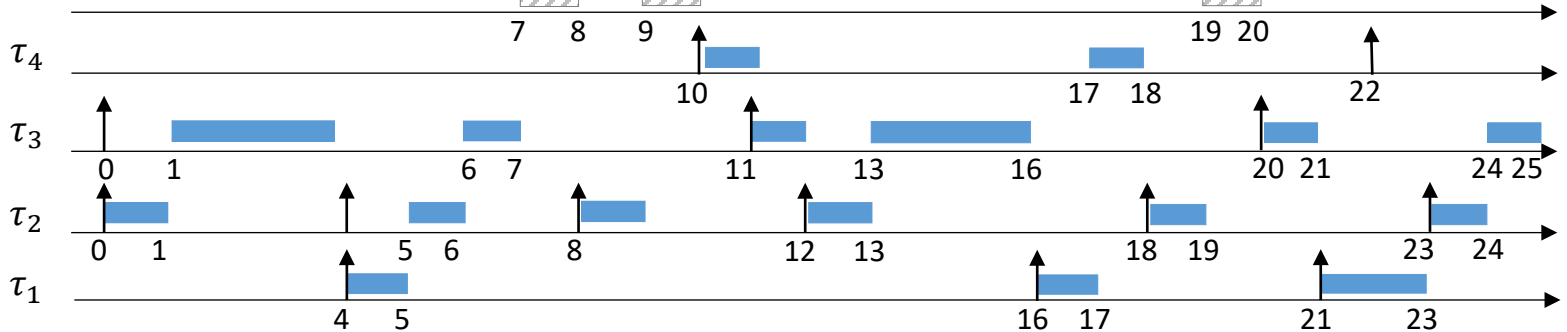
Schedule

medium-priority
periodic task with
release jitter

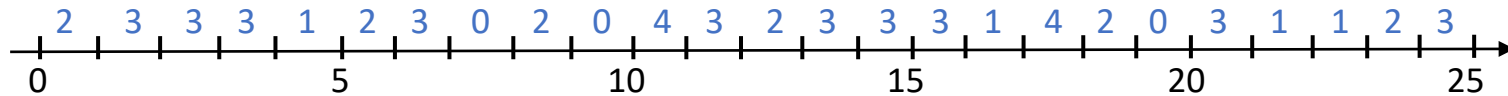
high-priority
sporadic task

high-priority
aperiodic task

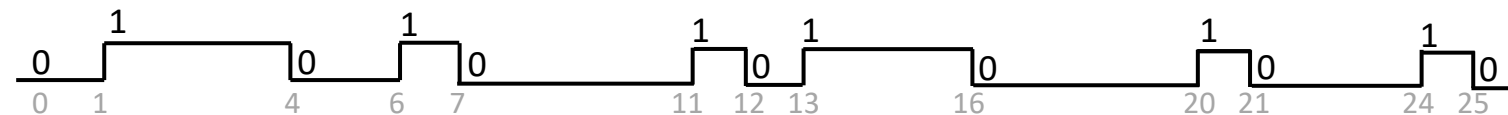
τ_0 (idle task)



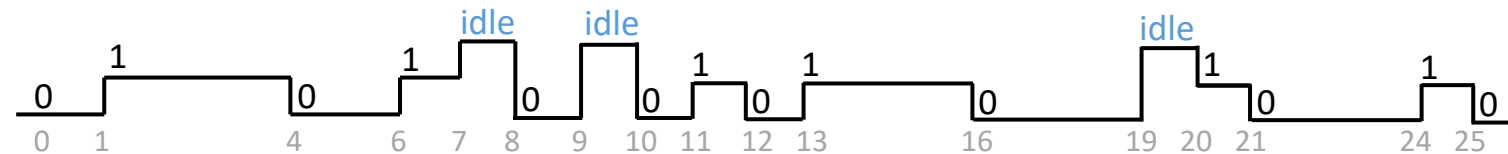
Trace



Binary projection of τ_3



Ternary projection of τ_3 (we see execution intervals of τ_3 and idle task)



Problem. Given a binary (or ternary) projection, find the period
(tell if τ_3 is still activated with the expected period)

The period inference problem



We do not know

- The **number** of tasks, **periods**, **offsets**, **execution times**, etc.
- **Scheduling** policy
- Presence of **preemptions** or **self suspensions**
- Existence of **timing uncertainties** (e.g., **release jitter**, **execution time variation**)
- Existence of **aperiodic tasks**
- Presence of **deadline misses** (for other tasks or the one we analyze)
- Presence of **overloads**
- ...

Can be obtained using simple monitoring tools like *top* command (in Linux) or by observing a CAN network

Other requirements

High accuracy

Robustness against uncertainties

Generic (works for any periodic system)

Low overhead and memory consumption

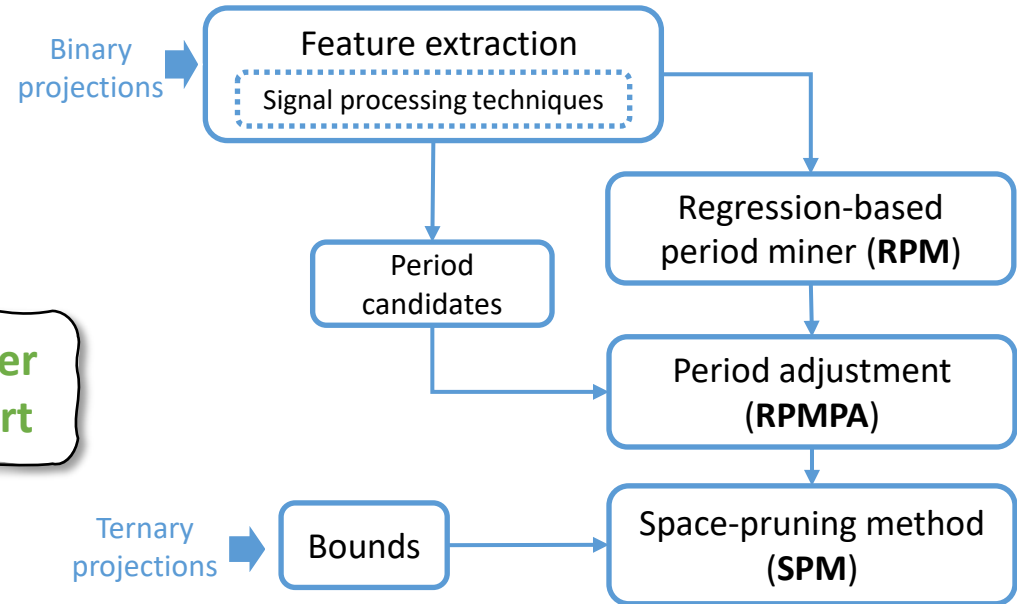
If it is a learning-based solution, then it must have **high accuracy even for systems that are different from what it has seen before**

Contributions

An open-source
period inference framework
based on regression-based techniques

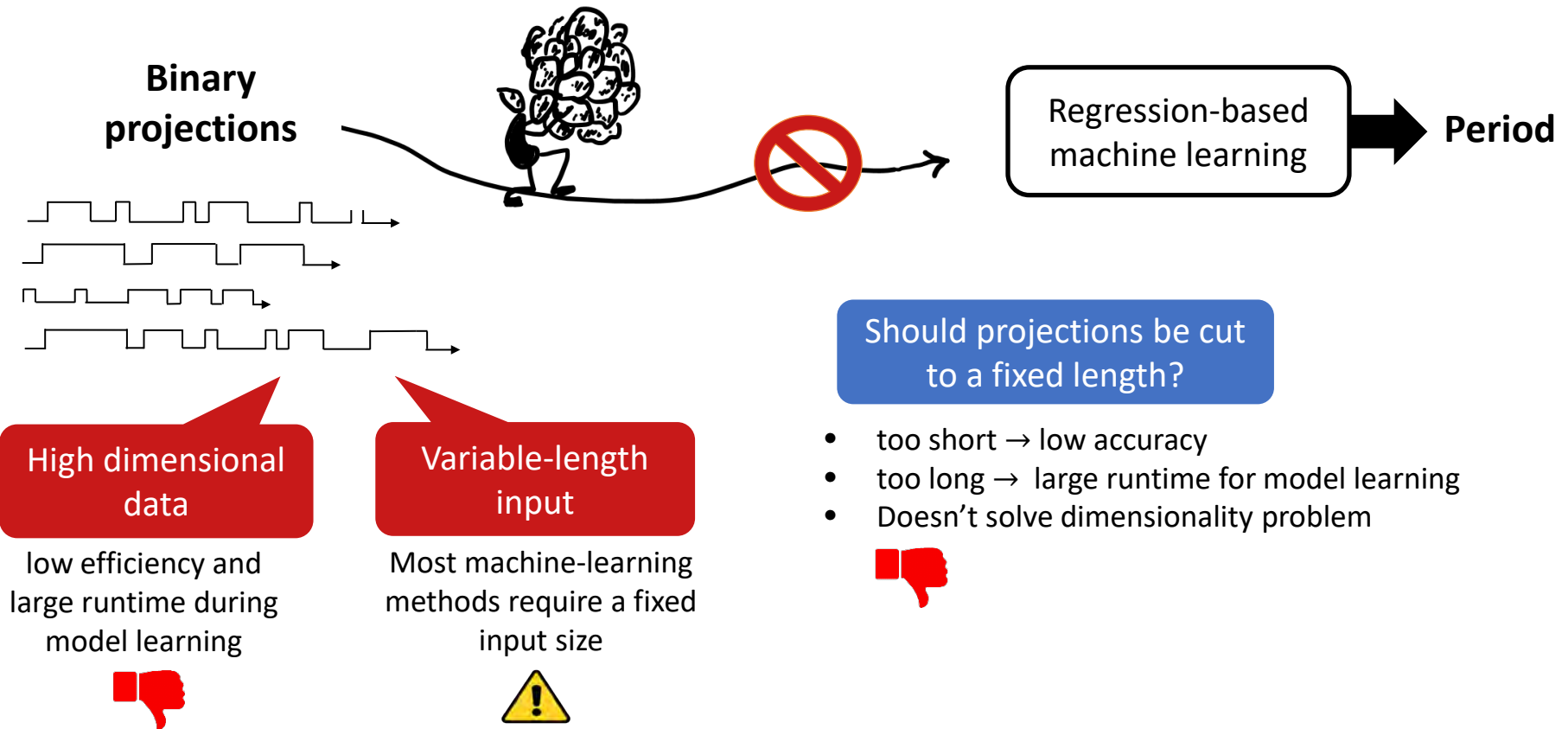
**2 to 3 orders of magnitude higher
accuracy than the state of the art**

A thorough investigation of
regression-based methods'
performance

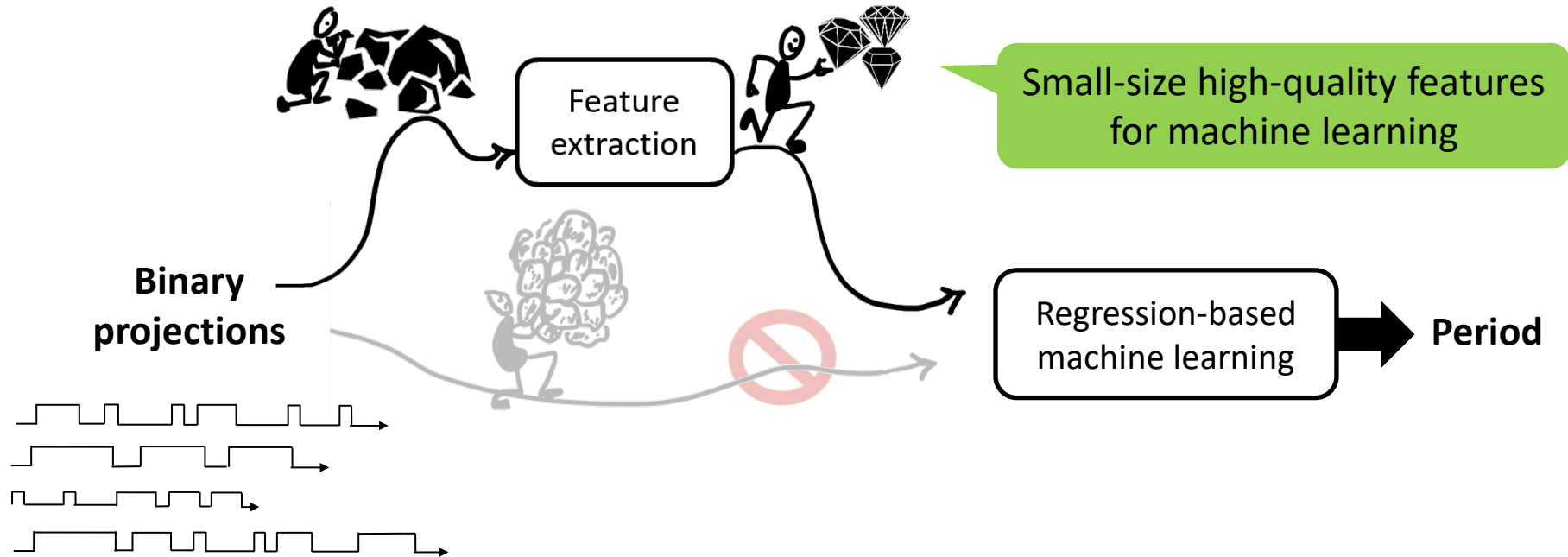


- **Accuracy**
- **Robustness** (in the presence of uncertainties)
- **Generalizability** (robustness w.r.t. new datasets)
- **Runtime cost** (overheads and memory)

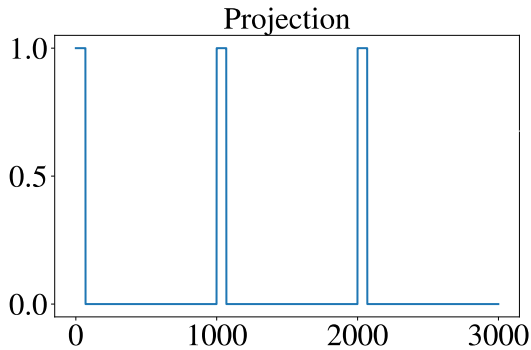
Why extracting features?



Why extracting features?

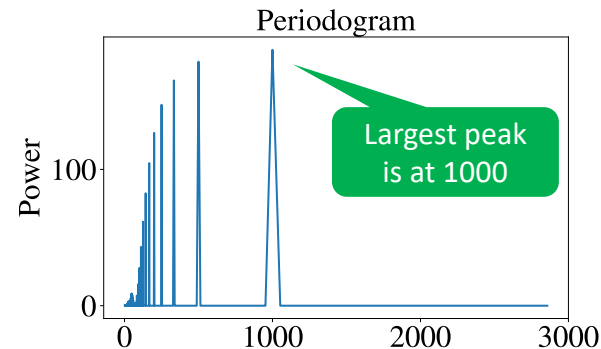


Feature extraction



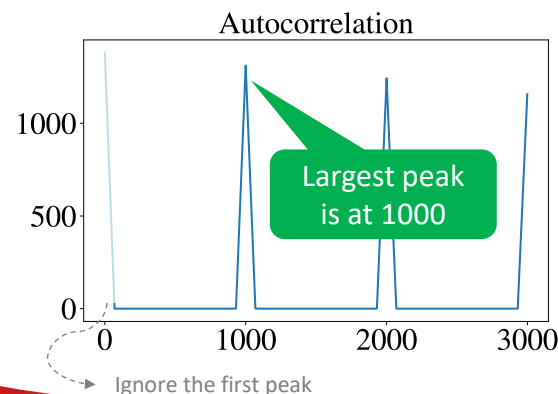
Projection of a high-priority task with period 1000

If these techniques are so good, why do we even need a regression-based solution?



Periodogram

- An estimate of the spectral density of the signal
- **How?**
Provided by the squared length of each Fourier coefficient of the signal

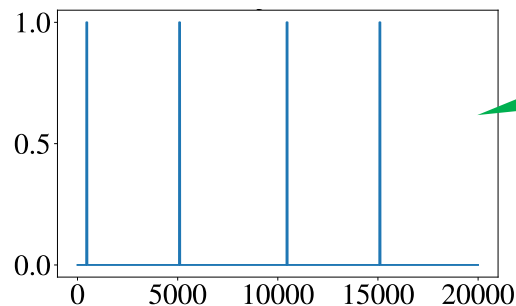


Circular autocorrelation

- Examines the similarity of a sequence to its previous values at different time lags
- **How?**
Inverse Fourier transform of dot product between the signal and its conjugation

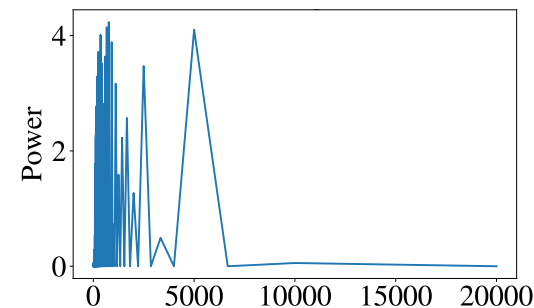
Challenges of feature extraction

Projection

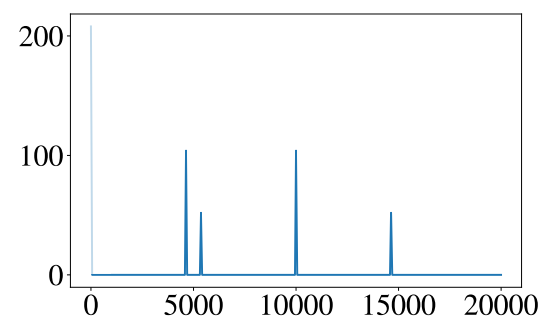


Projection of a low-priority task
with period 5000 (no preemption)

Periodogram



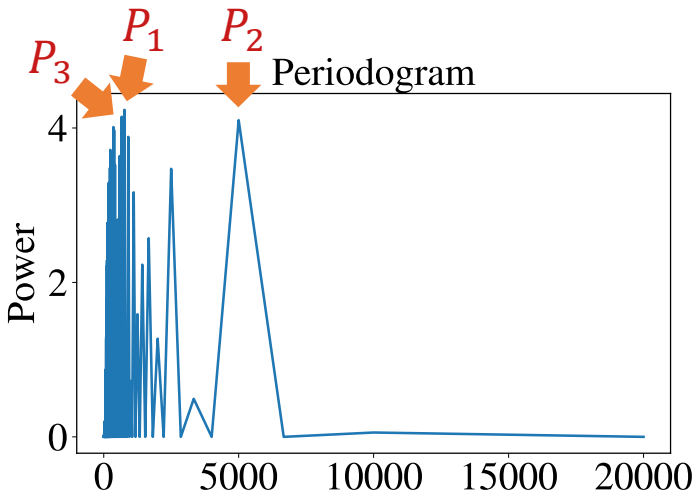
Autocorrelation



1. Have multiple peaks
2. The highest peak is not necessarily the period
3. May not even have a peak at the true period (e.g., in autocorrelation)

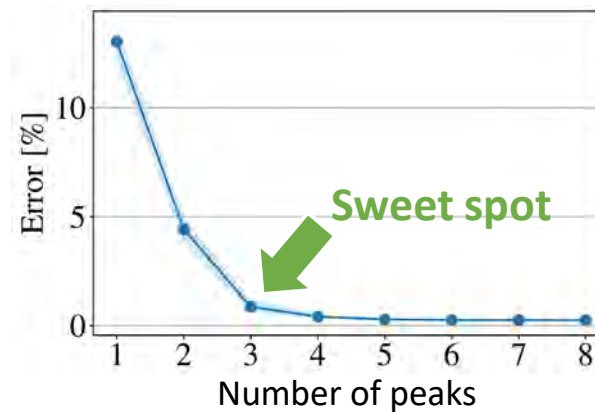
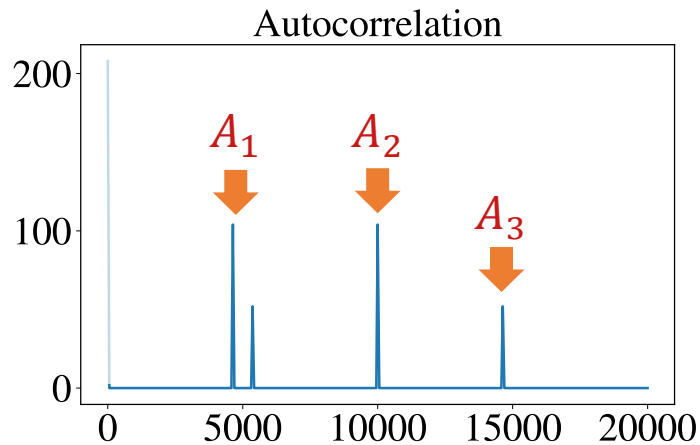


Features

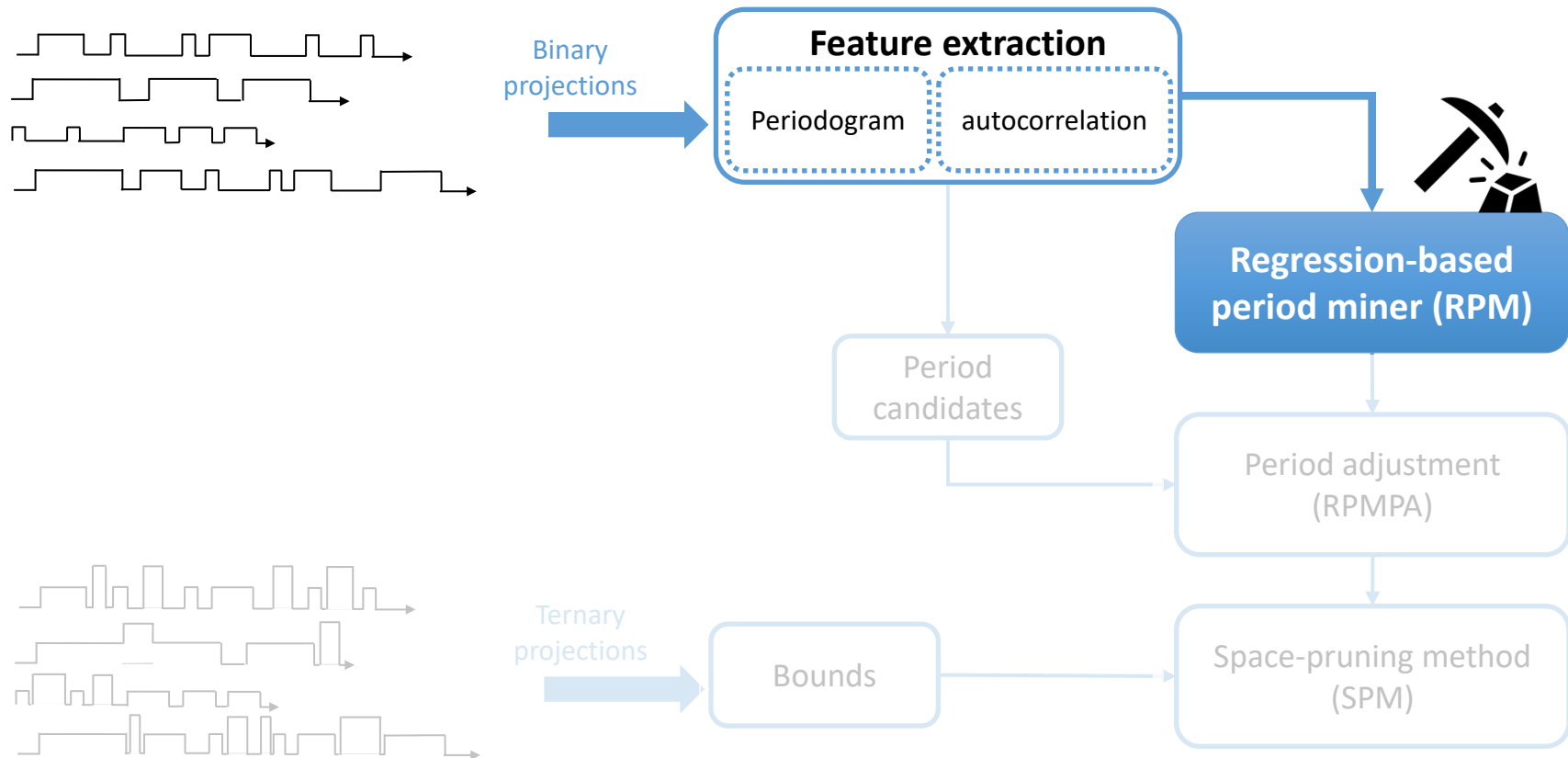


We select the **3** highest peaks from **Periodogram** and **3** highest peaks from **autocorrelation**

- Features for an input projection: $\{P_1, P_2, P_3, A_1, A_2, A_3\}$
- ✓ Small set
- ✓ Fixed size
- ✓ Independent of task's period, hyperperiod, projection length, etc.



Our solution in a nutshell



Regression-based period miner (RPM)

Features

- Top 3 periods from periodogram
- Top 3 periods from autocorrelation



Regression-based
machine learning



Period

Which **regression algorithm** would result in
a better accuracy for inferring periods?

M. Fernández-Delgado, M. S. Sirsat, E. Cernadas, S. Alawadi, S. Barro, and M. Febrero-Bande.
“**An extensive experimental survey of regression methods**”, Neural Networks, pp. 11-34, **2019**.

6 best families of
regression techniques

Algorithm	Nickname	Category
Cubist Regression [24]–[26]	<i>cubist</i>	Rule-based
Generalized Boosting Regression [27]	<i>gbm</i>	Boosting
Averaged Neural Network [28]	<i>avNNet</i>	Neural Networks
Extremely Randomized Regression Trees [29]	<i>extraTrees</i>	Random Forests
Bayesian Additive Regression Tree [30]	<i>bartMachine</i>	Bayesian Models
Support Vector Regression [31]	<i>svr</i>	Support Vector Machines

Which regression algorithms?

Cubist
regression

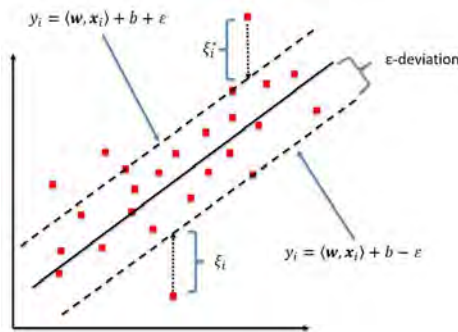
extremely randomized
regression trees
(extraTrees)

gradient boosting
method (gbm)

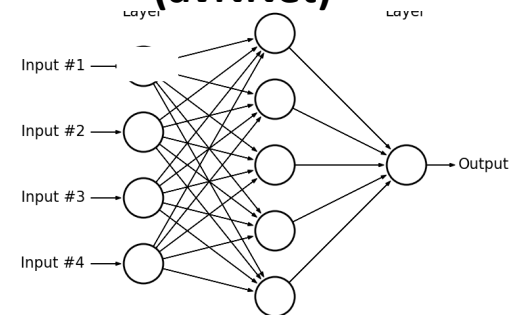
Bayesian additive
regression trees
(bartMachine)

Tree-based
algorithms

support vector regression
(svr)



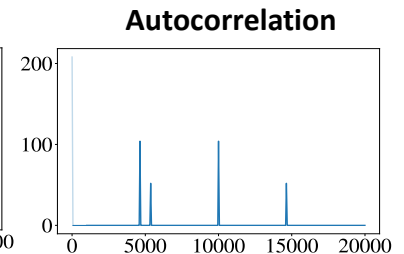
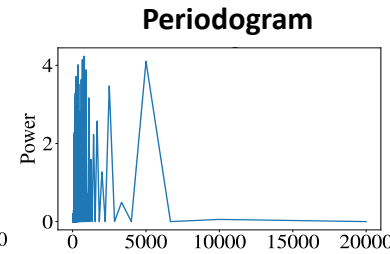
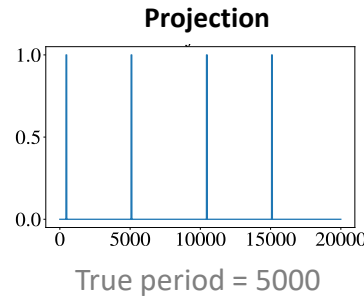
averaged neural networks
(avNNet)



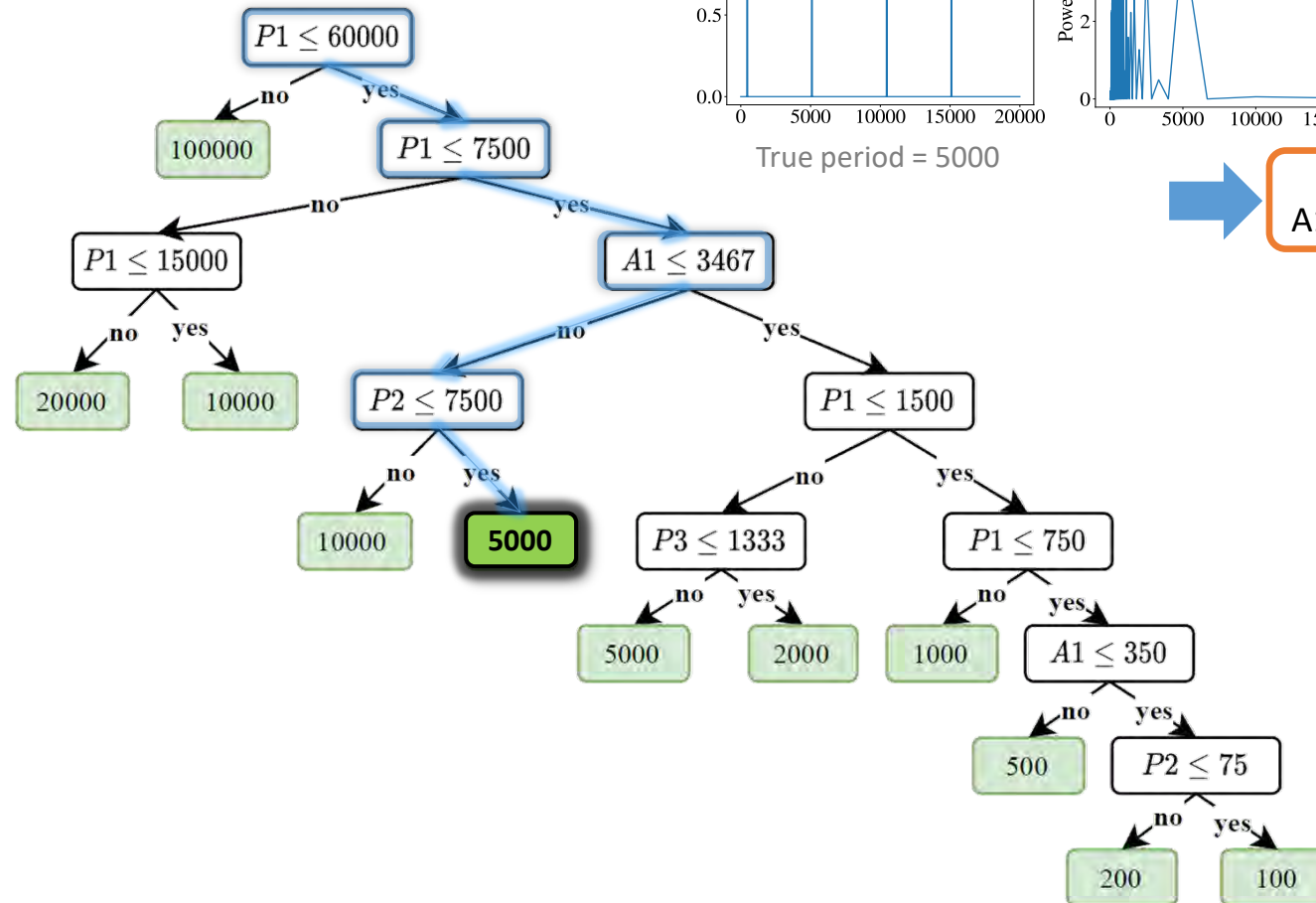
Cubist [Quinlan 1992, 1993, 2014]
ExtraTrees [Geurts 2006]
gbm [Friedman 2002]

bartMachine [Chipman 2010]
avNNet [Ripley 2007]
Svr [Cortes 1995]

What is a regression tree?



P1=769, P2=666, P3=5000,
A1=4635, A2=10000, A3=5365



P1, P2, P3 – top 3 periods from periodogram
A1, A2, A3 – top 3 periods from autocorrelation

Regression-tree based algorithms

Cubist regression

*Collapses the tree into a set of **rules***

extremely randomized regression trees

Trains multiple trees, averages the output

gradient boosting method (gbm)

Creates a tree to minimize the error of previous trees

Bayesian additive regression trees

Like gbm, reduces the error of previous trees using a probability model for the likelihood of leaf values

See the paper to learn more about them

Cubist [Quinlan 1992, 1993, 2014]
ExtraTrees [Geurts 2006]
gbm [Friedman 2002]

bartMachine [Chipman 2010]
avNNet [Ripley 2007]
Svr [Cortes 1995]

Evaluations

Evaluation questions

Did our solutions improve accuracy?

How do our solutions compare in terms of accuracy?



How do the six families of regression methods compare when applied on the period inference problem?

In terms of

- Accuracy, runtime, memory consumption, robustness against uncertainties, and learning robustness

RPM – regression-based period miner 
RPMPA – regression-based period miner with period adjustment 
SPM – space-pruning method 

Evaluations: datasets

automotive traces

Automotive benchmark application

- Task sets used in automotive domain [Krammer 2015]
- Periods from {1, 2, 5, 10, 20, 50, 100, 200, 1000}ms

log-uniform traces

Synthetic task sets

- Random periods chosen from [10, 1000] with log-uniform distribution [Emberson 2010]

Traces were generated by **Simso** simulator [Chéramy 2014].

Case study

Two datasets from message traces of the CAN bus of actual vehicles

Evaluations: metric and parameters

Accuracy

Period types

Number of tasks

System utilization

Release jitter

Execution time
variation

Robustness against uncertainties

Presence of high-priority
aperiodic tasks

Tasks may drop jobs

Generalizability of learning (a.k.a. learning robustness)

Impact of projection length on
testing's accuracy

Impact of training and testing on
different task set types

Impact of training and testing on
different task set sizes

Average
estimation error

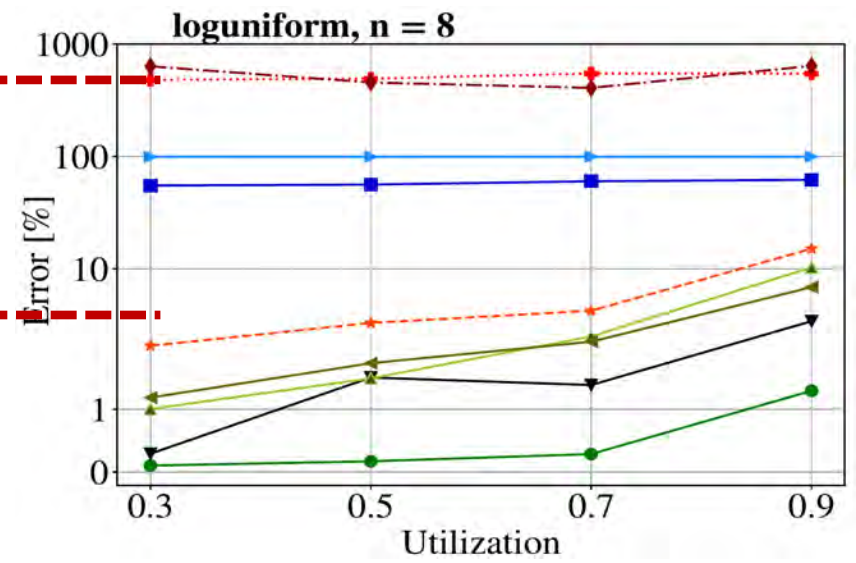
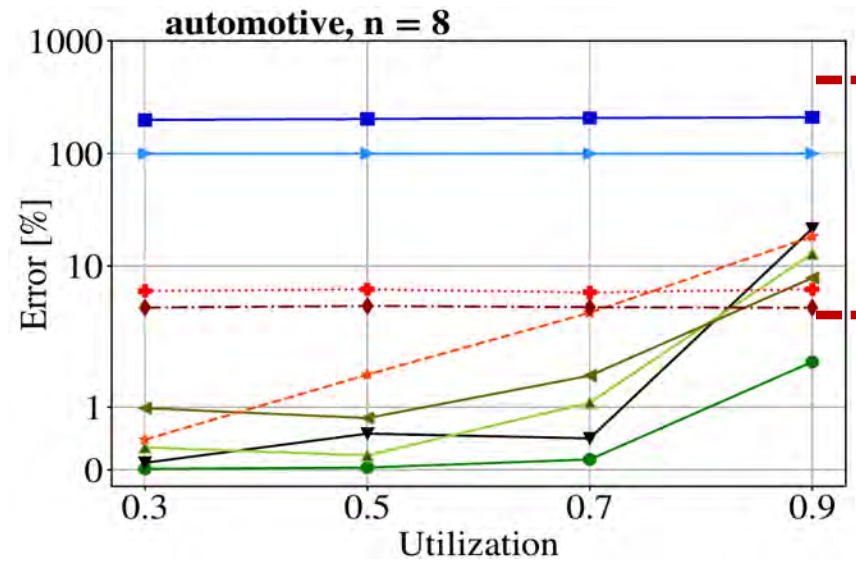
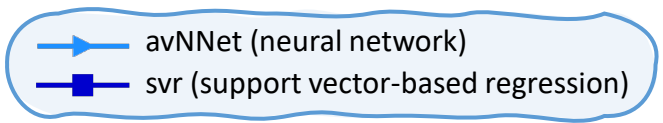
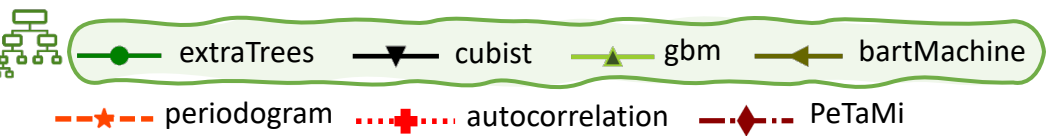
$$e = \frac{\sum_{i=1}^N \frac{\hat{T}_i - T_i}{T_i}}{N}$$

Estimated period

Actual periods

Number of tasks

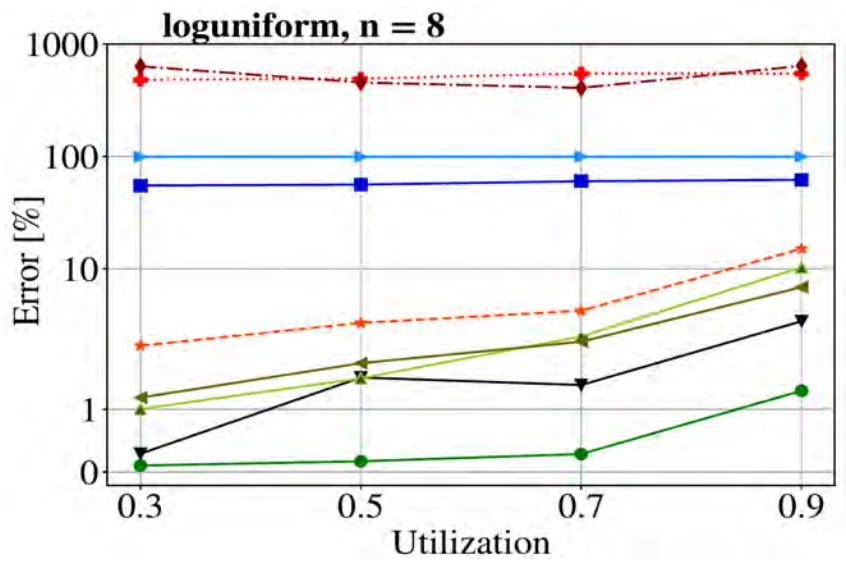
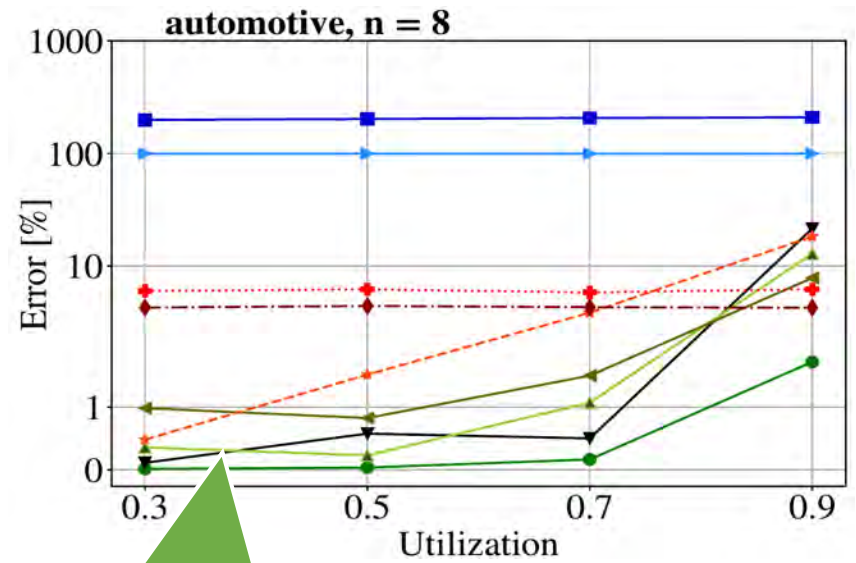
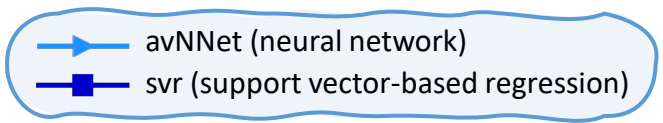
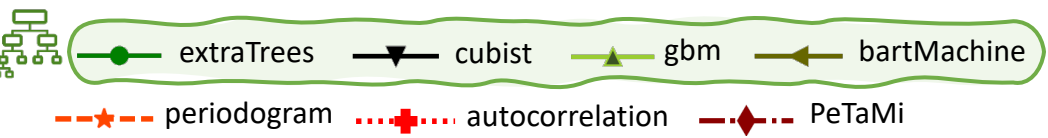
Impact of system utilization



120x increase in error for PeTaMi and autocorrelation

PeTaMi: O. Iegorov, R. Torres, and S. Fischmeister. "Periodic task mining in embedded system traces," RTAS, 2017.

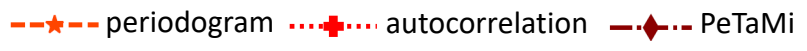
Impact of system utilization



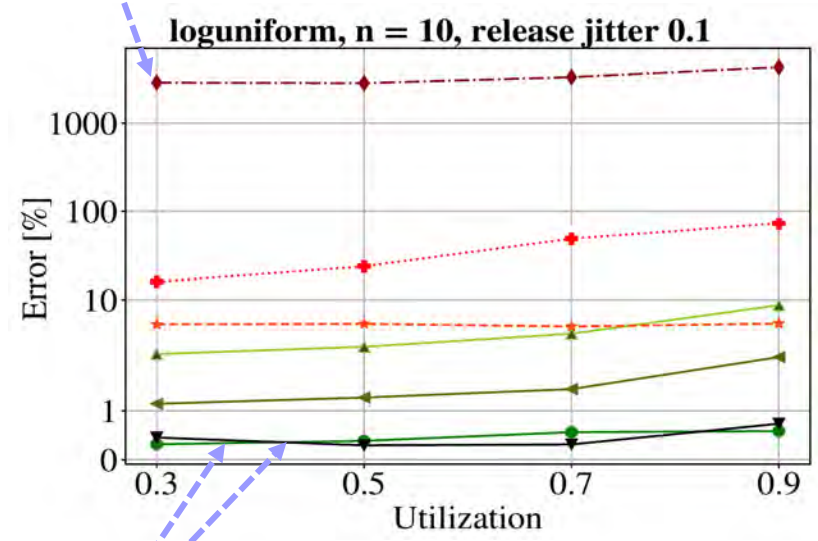
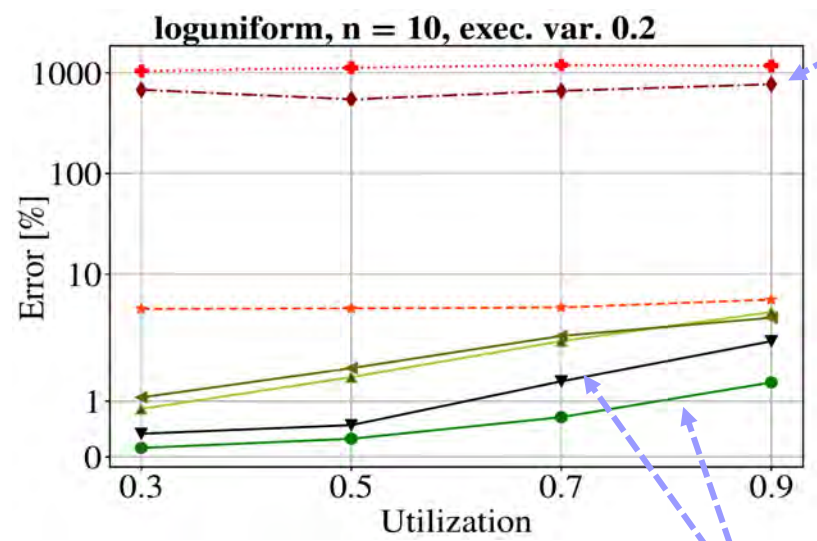
Tree-based solutions have high accuracy

PeTaMi: O. Iegorov, R. Torres, and S. Fischmeister. "Periodic task mining in embedded system traces," RTAS, 2017.

Robustness to variable execution time and release jitter



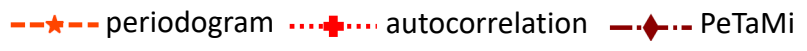
PeTaMi is heavily affected by **execution time variation** and **release jitter**



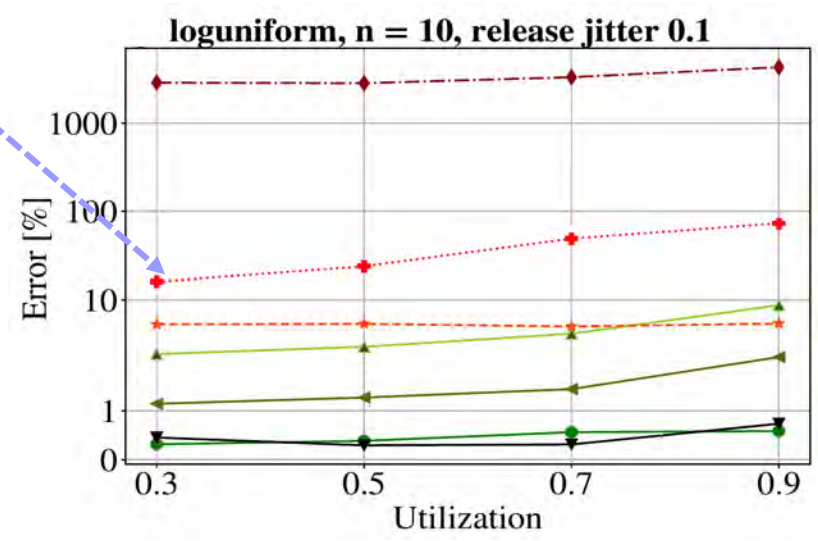
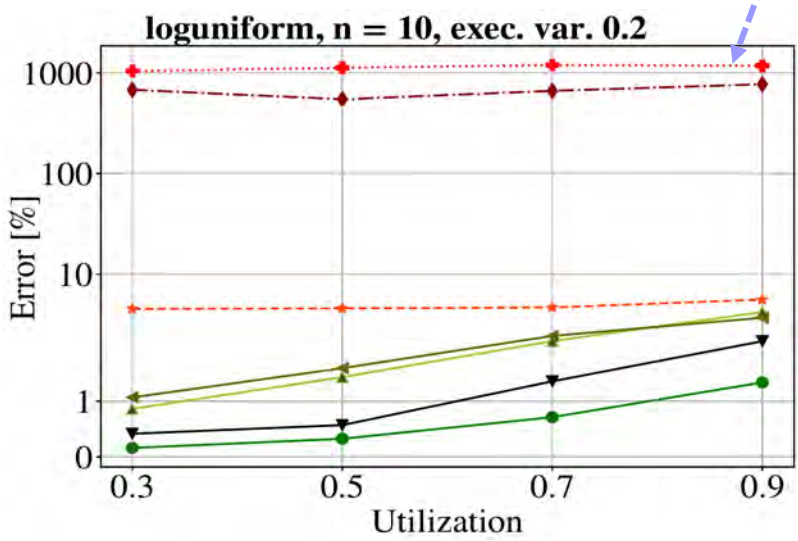
cubist and extraTrees are the most robust and most accurate solutions

Execution time $\in [(1 - \text{exec. var.}) \times \text{WCET}, \text{WCET}]$

Robustness to variable execution time and release jitter




Execution-time variation has a more negative impact on autocorrelation than release jitter



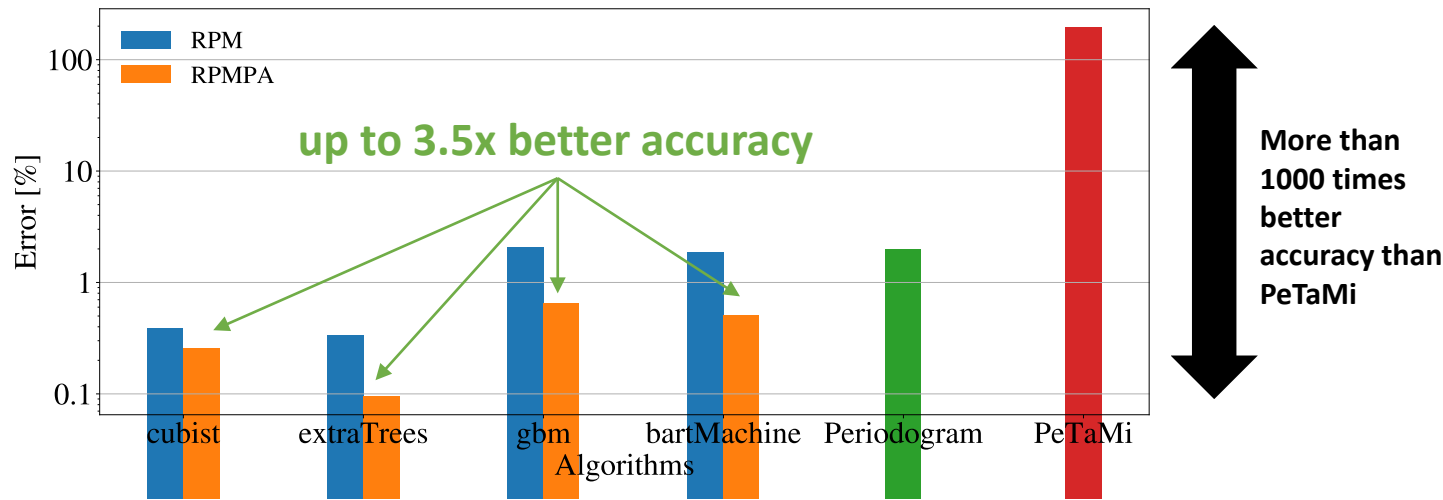
Execution time $\in [(1 - \text{exec. var.}) \times \text{WCET}, \text{WCET}]$



Robustness in the presence of high-priority aperiodic tasks

- 12 automotive tasks
 - 6 periodic
 - 6 sporadic
- Aperiodic jobs arrive according to a Poisson distribution. They preempt any of the 12 tasks.
- Here, the task under analysis has a medium priority

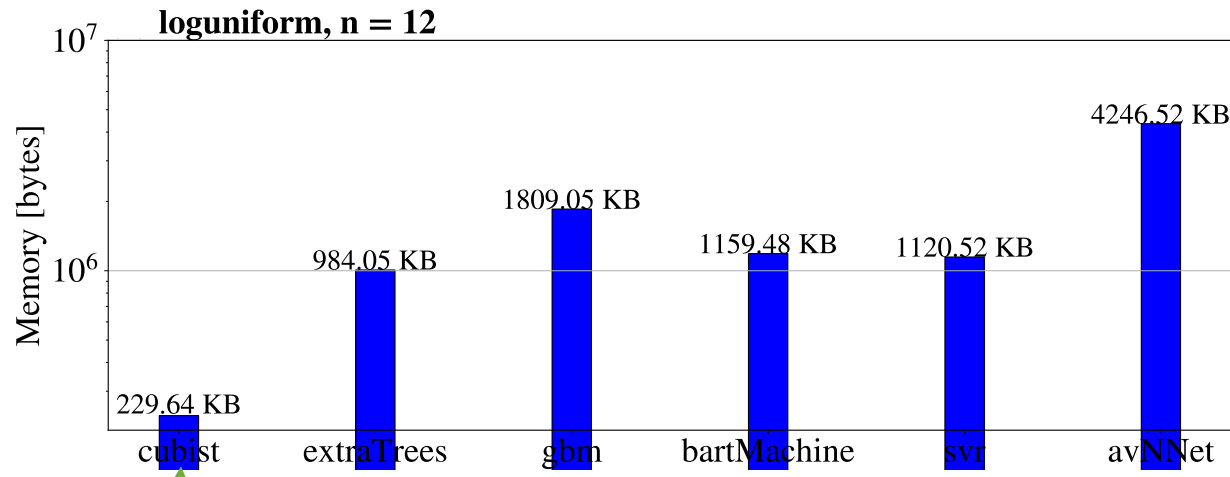


RPMPA reduces the error for all algorithms

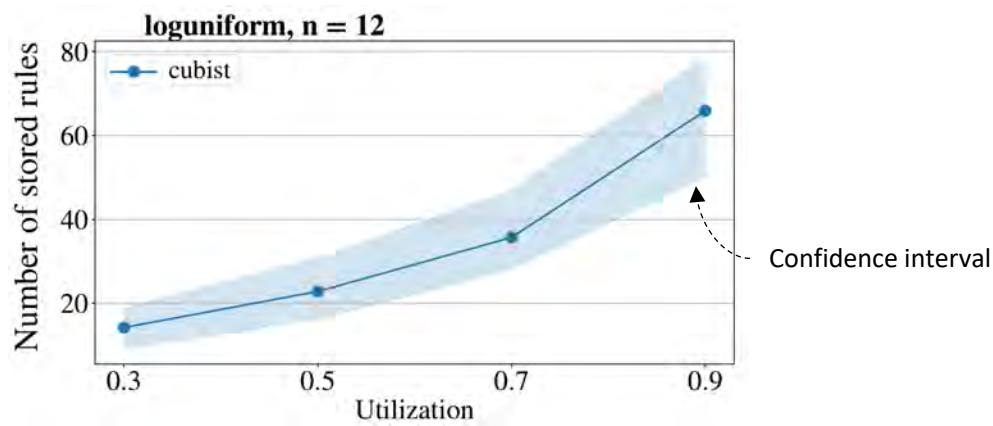


RPM – regression-based period miner 
RPMPA – regression-based period miner with period adjustment 

Memory comparison

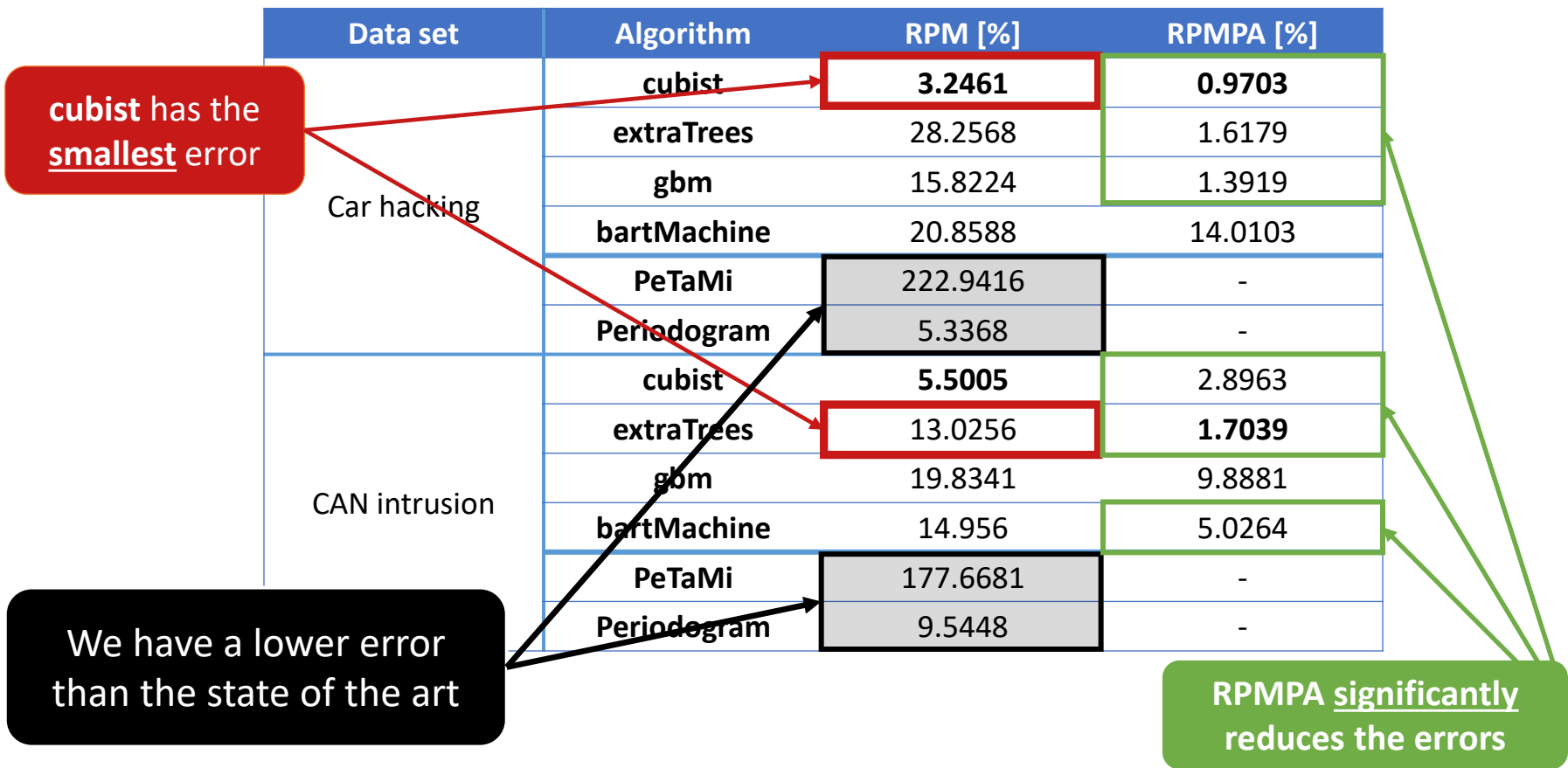


4x less memory consumption than extraTrees

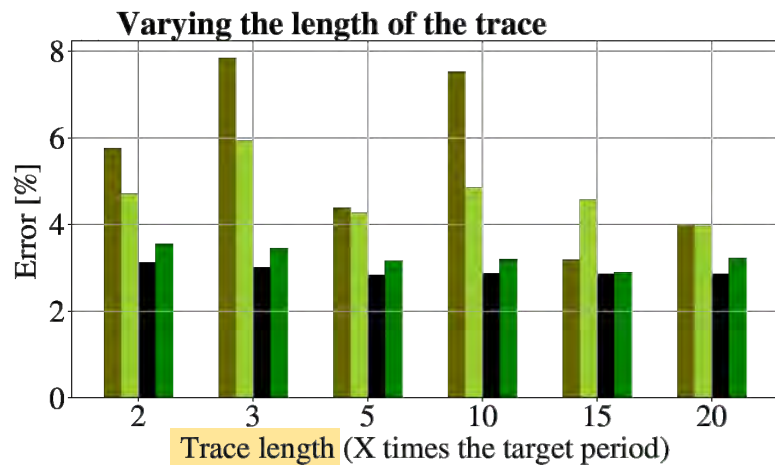
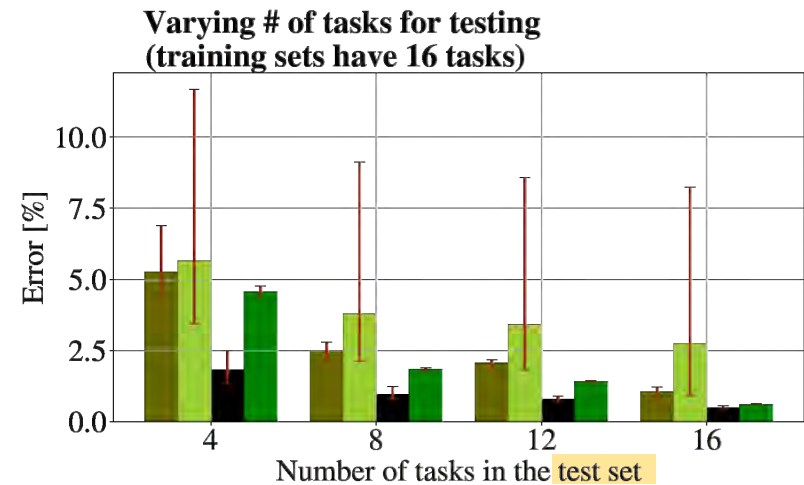
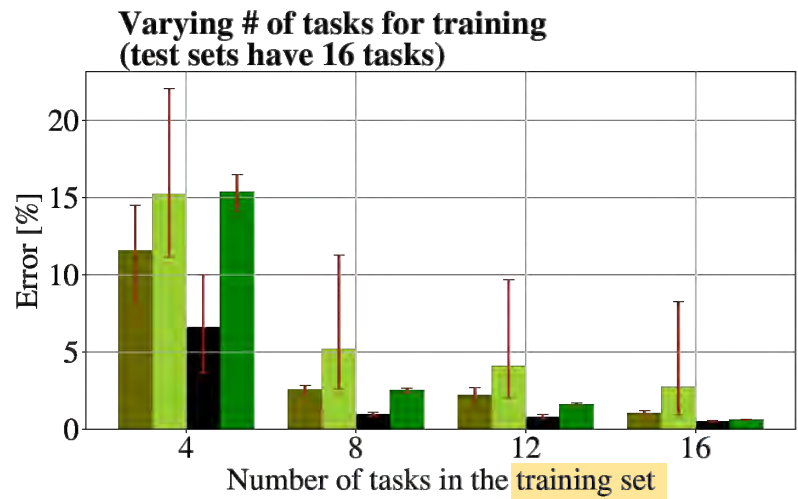


What is the performance on real data?

Two datasets containing controller area network (CAN) messages obtained from vehicles



Generalizability (robustness of learning)



Cubist and **extraTrees** maintain their accuracy in all these scenarios

Conclusions

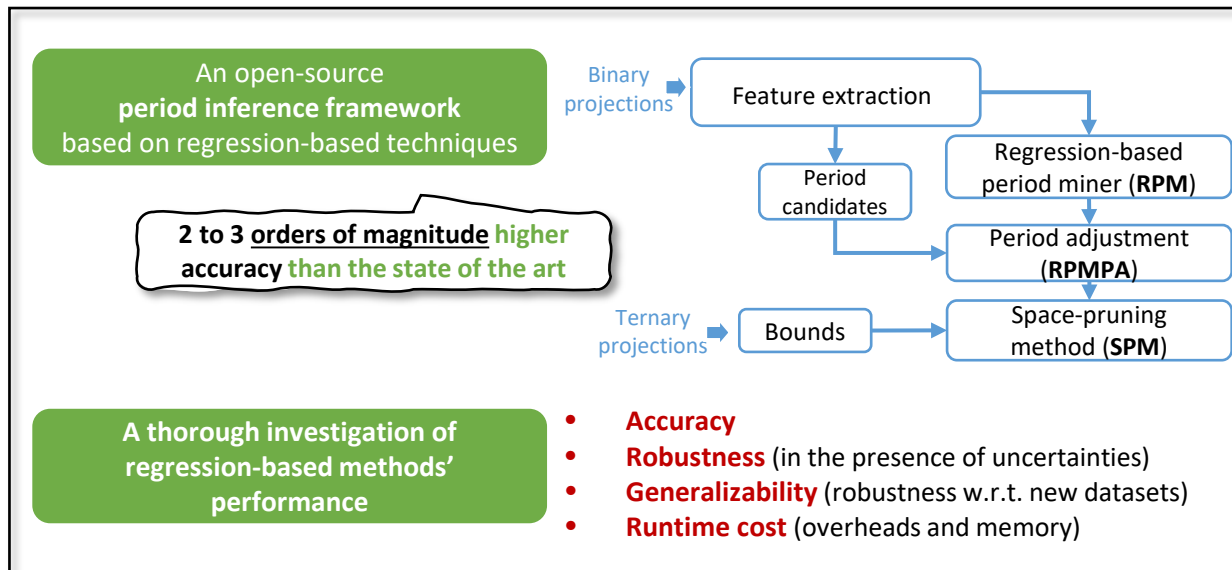
We showed how to use **regression-based machine learning (RBML)** for the problem of period inference

We reduce the **error** of period inference by **2 to 3 orders of magnitude** in comparison to other works

Our investigation showed that **Cubist regression** has:

- **the lowest** memory requirements;
- **the lowest** runtime;
- **the lowest** error on real traces.
- **It is robust and has a high learning robustness (generalizability)**

And have a smaller runtime



Source code:

https://github.com/SerbanVadineanu/period_inference

Slides of the talk at RTSS'2020:

https://drive.google.com/file/d/1ciUy_bJiSfmeqxeZCuA-hcS-aARl3AWe/view?usp=drive_link